

# Positive High-Voltage Power-Limiting Hotswap Controller With Analog Current Monitor Output

Check for Samples: TPS2492, TPS2493

#### **FEATURES**

- 9-V to 80-V Operation
- High-Side Drive for External N-FET
- Programmable FET Power Limit
- Programmable Load Current Limit
- Programmable Fault Timer
- Load Current Monitor Output
- Power Good and Fault Outputs
- Enable/UV, OV Inputs
- Latch or Auto Restart After Fault
- EVM Available SLUU425
- Calculation Tool Available SLVC033

#### **APPLICATIONS**

- Server Backplanes
- Storage Area Networks (SAN)
- Medical Systems
- Plug-in Modules
- Base Stations

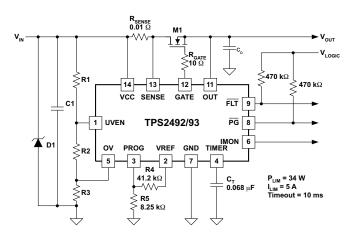
#### DESCRIPTION

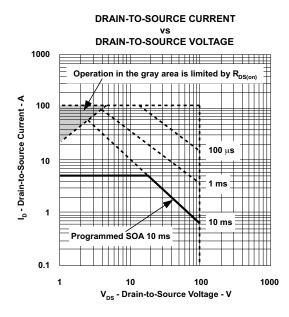
The TPS2492 and TPS2493 are easy-to-use, positive high voltage, 14-pin Hotswap Controllers that safely drive an external N-channel FET to control load current. The programmable power foldback protection ensures that the external FET operates inside its safe operating area (SOA) during overload conditions by controlling of power dissipation. The programmable current limit and fault timer ensure the supply, external FET, and load are not harmed by overcurrent. Features include inrush current limiting, controlled load turn-on, interfacing to down-stream DC-to-DC converters, and power feed protection.

The analog current monitor output provides a signal ready for sampling with an external A/D converter.

Additional features include programmable overvoltage and undervoltage shutdown, power-good for coordinating loads with inrush, and a fault indicator to indicate an over-current shutdown.

# **Typical Application Circuit**







Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.



#### PRODUCT INFORMATION(1)

TEMPERATURE	FUNCTION	PACKAGE	PART NUMBER
4000 +- 0500	Latched	DVA/4.4	TPS2492PW
-40°C to 85°C	Retry	PW14	TPS2493PW

 For the most current package and ordering information, see the Package Option Addendum at the end of this document, or visit the device product folder on www.ti.com.

# **ABSOLUTE MAXIMUM RATINGS(1)**

over recommended T<sub>1</sub> and voltages with respect to GND (unless otherwise noted)

		VALUE	UNIT
VCC, SENSE, UVEN, OUT	land valence reco	-0.3 to 100	
PROG, OV	Input voltage range	-0.3 to 6	
/CC – SENSE Differential voltage		-1.5 to 1.5	V
GATE, PG, FLT	Output voltage renge	-0.3 to 100	
TIMER, VREF, IMON	Output voltage range	-0.3 to 6	
PG, FLT	Circle asserts	10	
PROG	Sink current	2	mA
VREF	Source current	2	
НВМ	TCD roting	2	14/
CDM	ESD rating	0.5	kV

<sup>(1)</sup> Stresses beyond those listed under absolute maximum ratings may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under recommended operating conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

#### THERMAL INFORMATION

	THERMAL METRIC <sup>(1)</sup>	VALUE	UNITS
$\theta_{JA}$	Junction-to-ambient thermal resistance <sup>(2)</sup>	116.4	
$\theta_{JB}$	Junction-to-board thermal resistance (3)	53.8	9000
ΨЈТ	Junction-to-top characterization parameter <sup>(4)</sup>	1.4	°C/W
ΨЈВ	Junction-to-board characterization parameter <sup>(5)</sup>	58.8	

- (1) For more information about traditional and new thermal metrics, see the IC Package Thermal Metrics application report, SPRA953.
- (2) The junction-to-ambient thermal resistance under natural convection is obtained in a simulation on a JEDEC-standard, high-K board, as specified in JESD51-7, in an environment described in JESD51-2a.
- (3) The junction-to-board thermal resistance is obtained by simulating in an environment with a ring cold plate fixture to control the PCB temperature, as described in JESD51-8.
- (4) The junction-to-top characterization parameter, ψ<sub>JT</sub>, estimates the junction temperature of a device in a real system and is extracted from the simulation data for obtaining θ<sub>JA</sub>, using a procedure described in JESD51-2a (sections 6 and 7).
- (5) The junction-to-board characterization parameter, ψ<sub>JB</sub>, estimates the junction temperature of a device in a real system and is extracted from the simulation data for obtaining θ<sub>JA</sub>, using a procedure described in JESD51-2a (sections 6 and 7).

### RECOMMENDED OPERATING CONDITIONS

over recommended T<sub>J</sub> and voltages with respect to GND (unless otherwise noted)

		MIN	NOM	MAX	UNIT
VCC	Input valtage range	9		80	V
PROG	Input voltage range			4	V
VREF	Sourcing current	0		1	mA
VKEF	capacitive loading	0		1000	pF
IMON	Sourcing current			1.9	mA
TJ	Junction operating temperature	-40		125	°C



# **ELECTRICAL CHARACTERISTICS**

 $9 \text{ V} \le \text{V}_{\text{VCC}} \le 80 \text{ V}$ ,  $-40^{\circ}\text{C} \le \text{T}_{\text{J}} \le 125^{\circ}\text{C}$ ,  $\text{V}_{\text{TIMER}} = 0 \text{ V}$  and all outputs unloaded. Typical specification are at  $\text{T}_{\text{J}} = 25^{\circ}\text{C}$ ,  $\text{V}_{\text{VCC}} = 48 \text{ V}$  (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Supply C	Surrent (VCC)		·	·	·	
I <sub>VCC</sub>	Enabled	V <sub>UVEN</sub> = Hi, V <sub>SENSE</sub> = V <sub>OUT</sub> = V <sub>VCC</sub>		665	1000	
I <sub>VCC</sub>	Disabled	$V_{UVEN} = Lo, V_{SENSE} = V_{VCC}, V_{OUT} = 0$		120	250	μΑ
	pply UVLO (VCC)			"	"	
	V <sub>VCC</sub> turn on	Rising		8.4	8.8	V
	Hysteresis		50	100	150	mV
Current S	Sense Input (SENSE)					
I <sub>SENSE</sub>	Input bias current	V <sub>SENSE</sub> = V <sub>OUT</sub> = V <sub>VCC</sub>		7.5	20	μA
	e Voltage Output (VREF)	,		-		-
V <sub>REF</sub>	Reference voltage	0 ≤ I <sub>VREF</sub> ≤ 1 mA	3.9	4	4.1	V
	miting Input (PROG)	***************************************		ļ-	<del> </del>	
I <sub>PROG</sub>	Input bias current; device enabled; sourcing or sinking	0.4 ≤ V <sub>PROG</sub> ≤ 4 V V <sub>UVEN</sub> = 48 V			5	μA
R <sub>PROG</sub>	Pull down resistance; device disabled	I <sub>PROG</sub> = 200 μA; V <sub>UVEN</sub> = 0 V		375	600	Ω
Power Li	miting and Current Limiting (SENS	SE)				
	Current limit threshold	V <sub>PROG</sub> = 2.4 V; V <sub>OUT</sub> = 0 V; V <sub>VCC</sub> = 48 V	17	25	33	
	V <sub>(VCC-SENSE)</sub> with power limiting trip	V <sub>PROG</sub> = 0.9 V; V <sub>OUT</sub> = 30 V; V <sub>VCC</sub> = 48 V	17	25	33	mV
	Current limit threshold V <sub>(VCC-SENSE)</sub> without power limiting trip	V <sub>PROG</sub> = 4 V; V <sub>SENSE</sub> = V <sub>OUT</sub>	45	50	55	IIIV
t <sub>F_TRIP</sub>	Large overload response time to GATE low	$V_{PROG} = 4 \text{ V; } V_{OUT} = V_{SENSE}; V_{(VCC\text{-SENSE})}: 0$ rising to 200 mV; $C_{(GATE\text{-OUT})} = 2 \text{ nF;}$ $V_{(GATE\text{-OUT})} = 1 \text{ V}$			1.2	μs
TIMER O	peration (TIMER)	1 12 22 /		-		
		V <sub>TIMER</sub> = 0 V	17	27	36	
ISOURCE	TIMER source current	V <sub>TIMER</sub> = 0 V; T <sub>J</sub> = 25°C	22	27	32	
		V <sub>TIMER</sub> = 5 V	1.5	2.7	3.7	μΑ
I <sub>SINK</sub>	TIMER sink current	V <sub>TIMER</sub> = 5 V; T <sub>J</sub> = 25°C	2.1	2.7	3.1	
	TIMER upper threshold		3.9	4 0	4.1	
$V_{TIMER}$	TIMER lower reset threshold	TPS2492 only	0.96	1.00	1.04	V
D <sub>RETRY</sub>	Fault retry duty cycle	TPS2493 only	0.5	0.75	1	%
	icator Output (FLT)					
		I <sub>FLT</sub> = 2 mA		0.1	0.25	
	Low voltage (sinking)	I <sub>FLT</sub> = 4 mA		0.25	0.5	V
I <sub>LEAKAGE</sub>	Leakage current	FLT high impedance			10	μA
	oltage and Enable Input (UVEN)					
V <sub>UVEN_H</sub>		UVEN rising	1.31	1.35	1.39	V
O * E N_11	Threshold voltage	Hysteresis	80	100	120	mV
	Leakage current	V <sub>UVEN</sub> = 48 V			1	μA



# **ELECTRICAL CHARACTERISTICS (continued)**

 $9 \text{ V} \leq V_{\text{VCC}} \leq 80 \text{ V}$ ,  $-40^{\circ}\text{C} \leq T_{\text{J}} \leq 125^{\circ}\text{C}$ ,  $V_{\text{TIMER}} = 0 \text{ V}$  and all outputs unloaded. Typical specification are at  $T_{\text{J}} = 25^{\circ}\text{C}$ ,  $V_{\text{VCC}} = 48 \text{ V}$  (unloaded)

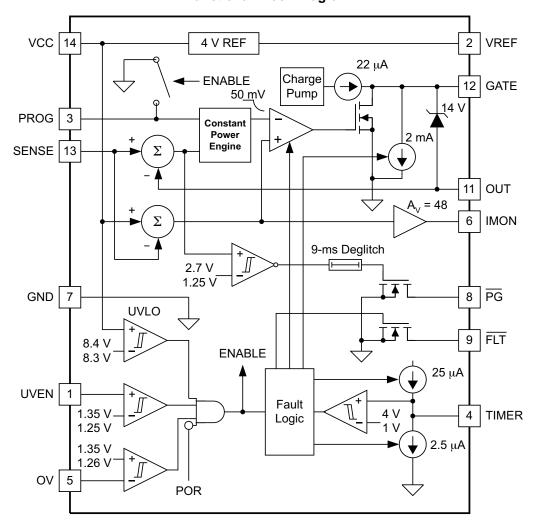
	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Gate Driv	e Output (GATE)		•			
	GATE sourcing current	V <sub>SENSE</sub> = V <sub>VCC</sub> ; V <sub>(GATE-OUT)</sub> = 7 V; V <sub>UVEN</sub> = Hi	15	22	35	μΑ
I <sub>GATE</sub>		V <sub>UVEN</sub> = Lo; V <sub>GATE</sub> = V <sub>VCC</sub>	1.8	2.4	2.8	
GATE	GATE sinking current	$V_{UVEN}$ = Hi; $V_{GATE}$ = $V_{VCC}$ ; $V_{VCC}$ - $V_{SENSE}$ = 200 mV	75	125	250	mA
$V_{GATE}$	GATE output	$V_{UVEN}$ = Hi, VCC = SENSE = OUT, measure $V_{GATE}$ - $V_{OUT}$	12		16	V
t <sub>D_ON</sub>	Propagation delay: UVEN going high to GATE output high	$V_{UVEN}$ = 0 $\rightarrow$ 2.5 V, 50% of $V_{UVEN}$ to 50% of $V_{GATE}$ , $V_{OUT}$ = $V_{VCC}$ , $R_{(GATE-OUT)}$ = 1 $M\Omega$		25	40	
t <sub>D_OFF</sub>	Propagation delay: UVEN going low to GATE output low	$\begin{aligned} &V_{UVEN} = 2.5 \ V \rightarrow 0 \ V, \ 50\% \ of \ V_{UVEN} \ to \ 50\% \\ &of \ V_{GATE}, \ V_{OUT} = V_{VCC}, \ R_{(GATE-OUT)} = 1 \ M\Omega, \\ &t_{FALL} < 0.1 \ \mu s \end{aligned}$		0.5	1	μs
t <sub>D_FAULT</sub>	Propagation delay: TIMER expires to GATE output low	$\begin{array}{l} V_{TIMER}\colon 0\to 5~V,~t_{RISE}<0.1~\mu s.~50\%~of\\ V_{TIMER}~to~50\%~of~V_{GATE},~V_{OUT}=VCC~,\\ R_{(GATE-OUT)}=1~M\Omega, \end{array}$		0.8	1	
Power Go	ood Output ( <del>PG</del> )					
	Low voltage (sinking)	I <sub>PG</sub> = 2 mA		0.1	0.25	
	Low voitage (sirking)	$I_{\overline{PG}} = 4 \text{ mA}$		0.25	0.5	
	PG threshold voltage; V <sub>OUT</sub> rising; PG goes low	$V_{SENSE} = V_{VCC}$ ; measure $V_{(VCC-OUT)}$	0.8	1.25	1.7	V
	PG threshold voltage; V <sub>OUT</sub> falling; PG goes open drain	$V_{SENSE} = V_{VCC}$ ; measure $V_{(VCC-OUT)}$	2.2	2.7	3.2	·
	PG threshold hysteresis voltage; V(SENSE-OUT)	V <sub>SENSE</sub> = V <sub>VCC</sub>		1.4		
t <sub>DPG</sub>	PG deglitch delay; detection to output; rising and falling edges	V <sub>SENSE</sub> = V <sub>VCC</sub>	5	9	15	ms
I <sub>LEAKAGE</sub>	Leakage current; PG false	open drain			10	μA
Overvolta	age Input (OV)		·		·	
V <sub>OV_H</sub>	Throchold voltage	OV rising	1.31	1.35	1.39	V
	Threshold voltage	Hysteresis	70	90	110	mV
I <sub>LEAKAGE</sub>	Leakage current (sinking)	V <sub>OV</sub> = 5 V			1	μΑ
t <sub>OFF</sub>	Turn off time	$V_{OV}$ = 0 $\rightarrow$ 2.5 V to $V_{GS}$ < 1 V, $C_{GATE}$ = 2 nF			2	
	Maximum duration of OV strong pull down	Gate pull down	40	100	220	μs
Output V	oltage Feedback (OUT)					
I	Rice current	$V_{OUT} = V_{VCC}, V_{UVEN} = Hi; sinking$		8	20	μΑ
l <sub>OUT</sub>	Bias current	V <sub>OUT</sub> = GND; V <sub>UVEN</sub> = Lo; sourcing		18	40	μΛ
Load Cur	rent Monitor (IMON) Output					
	Maximum output voltage	$V_{CC} - V_{SENSE} = 200 \text{ mV}$	2.6	2.8	3	V
I <sub>SOURCE</sub>	Source current		1.9			mA
I <sub>SINK</sub>	Sink current			60		μΑ
	Gain (V <sub>IMON</sub> /V <sub>(VCC-SENSE)</sub> )		46	48	50	V/V
V <sub>OFFSET</sub>	Offset voltage		-50	-5	30	mV
	Linearity <sup>(1)</sup>	Error relative to curve fit, 5 mV < (V <sub>CC</sub> - V <sub>SENSE</sub> )		0.3%		
	Output Ripple <sup>(1)</sup>			8		$mV_{PP}$

<sup>(1)</sup> These parameters are provided for reference only, and do not constitute part of Tl's published device specifications for purposes of Tl's product warranty.



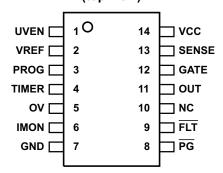
## **DEVICE INFORMATION**

# **Functional Block Diagram**





# PW PACKAGE (top view)



# **TERMINAL FUNCTIONS**

TERMINAL		1/0	DESCRIPTION			
NAME	NO.	I/O	DESCRIPTION			
UVEN	1	I	A low input inhibits GATE. A logic input can drive this pin as an enable.			
VREF	2	0	4-V reference voltage used to set the power threshold on PROG pin.			
PROG	3	I	FET power-limit programming pin			
TIMER	4	I/O	A capacitor from TIMER to ground sets the fault timer period.			
OV	5	I	Overvoltage sensing input. A high input inhibits GATE.			
IMON	6	0	Current monitor output, nominally V <sub>IMON</sub> = 48 x (V <sub>VCC-SENSE</sub> ).			
GND	7	PWR	Ground			
PG	8	0	Active low power good output. This is driven by V <sub>VCC-SENSE</sub> .			
FLT	9	0	Active low fault indicator output. FLT indicates the fault timer has expired. FLT is reset by UVEN, UVLO, or automatic restart.			
NC	10		No connect			
OUT	11	1	FET source voltage (output) sensing pin. Gate is clamped to a diode drop below OUT.			
GATE	12	0	Gate driver output for external FET.			
SENSE	13	I	Current sensed as $V_{VCC\text{-SENSE}}$ and the FET $V_{DS}$ as $V_{SENSE\text{-OUT}}$ . For low FET $V_{DS}$ , current limits at 50mV.			
VCC	14	I	Input supply and current sense positive input			



#### DETAILED PIN DESCRIPTION

The following description relies on the Typical Application Diagram shown on page 1, and the Functional Block Diagram.

**VCC:** This pin is associated with three functions:

- 1. Biasing power to the integrated circuit,
- 2. Input to power on reset (POR) and under-voltage lockout (UVLO) functions, and
- 3. Voltage sense at one terminal of R<sub>SENSE</sub> for M1 current measurement.

The voltage must exceed the POR (about 6 V for roughly 400  $\mu$ s) and the internal UVLO (about 8 V) before normal operation (driving the GATE) may begin. Connections to VCC should be designed to minimize R<sub>SENSE</sub> voltage sensing errors and to maximize the effect of C1 and D1; place C1 at R<sub>SENSE</sub> rather than at the device pin to eliminate transient sensing errors. GATE, PROG, and TIMER are held low when either UVLO or POR are active. PG and FLT are open drain when either UVLO or POR are active.

**SENSE:** Monitors the voltage at the drain of M1, and the downstream side of  $R_{SENSE}$  providing the constant power limit engine with feedback of both M1 current ( $I_D$ ) and voltage ( $V_{DS}$ ). Voltage is determined by the difference between SENSE and OUT, while the current analog is the voltage difference between VCC and SENSE. The constant power engine uses  $V_{DS}$  to compute the allowed  $I_D$  and is clamped to 50 mV, acting like a traditional current limit at low  $V_{DS}$ . The current limit is set by the following equation:

$$I_{\text{LIM}} = \frac{50\text{mV}}{R_{\text{SENSE}}} \tag{1}$$

Design the connections to SENSE to minimize R<sub>SENSE</sub> voltage sensing errors. Don't drive SENSE to a large voltage difference from VCC because it is internally clamped to VCC. The current limit function can be disabled by connecting SENSE to VCC.

**GATE:** Provides the high side (above VCC) gate drive for external N-channel FET. It is controlled by the internal gate drive amplifier, which provides a pull-up of 22 µA from an internal charge pump and both strong (125 mA) and weak (2 mA) pull-downs to ground. The strong pull down is triggered by an overvoltage on the OV pin or large overcurrent to the load. The strong pull-down current is a non-linear function of the gate amplifier overdrive; it provides small drive for small overloads, but large overdrive for fast reaction to an output short. There is a separate pull-down of 2 mA to shut the MOSFET off when UVEN or UVLO cause this to happen. If an output short causes the VCC to fall below the UVLO, the turnoff speed will be limited by the 2mA turnoff current. An internal clamp protects the gate of the FET (to OUT).

**OUT:** This input pin is used by the constant power engine and the  $\overline{PG}$  comparator to measure  $V_{DS}$  of M1 as  $V_{(SENSE-OUT)}$ . Internal protection circuits leak a small current from this pin when it is low. If the load circuit can drive OUT below ground, connect a clamp (or freewheel) diode from OUT (cathode) to GND (anode). The diode should clamp the output above -1 V during the transient.

**UVEN:** The positive threshold of UVEN must be exceeded before the GATE driver is enabled. If the UVEN pin drops below the UVEN negative threshold while the GATE driver is enabled, the GATE driver will be pulled to GND by the 2-mA pull down. UVEN can be used as a logic control input, an analog input voltage monitor as illustrated by R1, R2 and R3 in the Typical Application Circuit, or it can be tied to VCC to always enable the TPS2492/3. The hysteresis associated with the internal comparator makes this a stable method of detecting a low input condition and shutting the downstream circuits off. A TPS2492 that has latched off can be reset by cycling UVEN below its negative threshold and back high.



**VREF**: Provides a 4.0-V reference voltage for use in conjunction with R4/R5 of the Typical Application Circuit to set the voltage on the PROG pin. The reference voltage is available once the internal POR and UVLO thresholds have been met. It is not designed as a supply voltage for other circuitry, therefore ensure that no more than 1 mA is drawn. Bypass capacitance is not required, but if a special application requires one, less than 1000 pF can be placed on this pin. This limit maintains VREG regulator stability.

**PROG:** The voltage applied to this pin (0.4 V minimum) programs the power limit used by the constant power engine. Normally, a resistor divider R4/R5 is connected from VREF to PROG to set the power limit according to the following equation:

$$V_{PROG} = \frac{P_{LIM}}{10 \times I_{LIM}} \tag{2}$$

where  $P_{LIM}$  is the desired power limit of M1 and  $I_{LIM}$  is the current limit set point (see SENSE).  $P_{LIM}$  is determined by the desired thermal stress on M1:

$$P_{\text{LIM}} < \frac{T_{\text{J(MAX)}} - T_{\text{S(MAX)}}}{R_{\Theta \text{JC(MAX)}}} \tag{3}$$

where  $T_{J(MAX)}$  is the maximum desired transient junction temperature of M1 and  $T_{S(MAX)}$  is the maximum case temperature prior to a start or restart.  $V_{PROG}$  is used in conjunction with  $V_{DS}$  to compute the (scaled) current,  $I_{D\_ALLOWED}$ , by the constant power engine.  $I_{D\_ALLOWED}$  is compared by the gate amplifier to the actual  $I_{D}$ , and used to generate a gate drive. If  $I_{D} < I_{D\_ALLOWED}$ , the amplifier turns the gate of M1 full on because there is no overload condition; otherwise GATE is regulated to maintain the  $I_{D} = I_{D\_ALLOWED}$  relationship.

A capacitor may be tied from PROG to ground to alter the natural constant power inrush current shape. If properly designed, the effect is to cause the leading step of current in Figure 13 to look like a ramp. It is not recommended that this mechanism be used to achieve a long and low ramp inrush current because the power limiting accuracy is lower at  $V_{PROG} < 0.4 \text{ V}$ . PROG is internally pulled to ground whenever UVEN, POR, or UVLO are not satisfied or the TPS2492 is latched off. This feature serves to discharge any capacitance connected to the pin. Do not apply voltages greater than 4 V to PROG. If the constant power limit is not used, PROG should be tied to VREF through a 47-k $\Omega$  resistor.

**TIMER:** An integrating capacitor,  $C_T$ , connected to the TIMER pin sets the fault-time for both versions and the restart interval for the TPS2493. The timer charges at 27 μA whenever the TPS2492/3 is in power limit or current limit and discharges at 2.7 μA otherwise. The charge-to-discharge current ratio is constant with temperature even though there is a positive temperature coefficient to both. If  $V_{TIMER}$  reaches 4 V, the TPS2492/3 pulls GATE to ground (with the strong pull down), and discharges  $C_T$ . The TPS2492 latches off when the fault timer expires. The TPS2493 holds GATE at ground when the timer expires before it attempts to restart (re-enable GATE) after a timing sequence consisting of discharging TIMER down to 1 V followed by 15 more charge and discharge cycles. Design for the TPS2393 TIMER period must assume a 3-V rise in  $V_{TIMER}$  rather than a 4-V rise to accommodate a restart.

The TPS2492 can be reset by either cycling the UVEN pin or the UVLO (e.g. power cycling). TIMER discharges when UVEN is low or the internal UVLO or POR are active. The TIMER pin should be tied to ground if this feature is not used.



PG: The power good output is an active low, open-drain output intended to interface to downstream DC-to-DC converters or monitoring <u>circ</u>uits.  $\overline{PG}$  goes low after  $V_{DS}$  of M1 has fallen to about 1.25 V and a 9-ms deglitch time period has elapsed.  $\overline{PG}$  is open drain whenever UVEN is low,  $V_{DS}$  of M1 is above 2.7 V, or UVLO is active. PG can also be viewed as having an output voltage monitor function. The 9-ms deglitch circuit operates to filter short events that could cause PG to go inactive (open drain) such as a momentary overload or input voltage step.  $V_{PG}$  can be greater than  $V_{VCC}$  because it's ESD protection is only with respect to ground.  $\overline{PG}$  may be left open or tied to GND if not used.

**GND:** This pin is connected to system ground.

IMON: This current monitor output has a voltage equal to 48 times the voltage across R<sub>SENSE</sub> (V<sub>VCC-SENSE</sub>). IMON is clamped at 2.7 V to prevent damage to downstream A/D circuits. IMON is a voltage output and does not require a pull up or pull down. IMON will have a small amount of superimposed ripple at 2.5 kHz that is an artifact of the monitoring circuit. The error due to the ripple does not significantly effect accuracy for signals on the order of 1 V, but better accuracy may be achieved for small signals with an external R-C filter. The IMON pull up source is stronger than the pull down. A resistor pull down can be used to improve transient response in designs with large filter capacitors. Leave IMON open if not used.

A curve of Linearity (%) versus V<sub>VCC-SENSE</sub> is provided in the Typical Characteristics, providing an indication of error versus signal level. This curve is constructed by first performing a first order curve fit to V<sub>IMON</sub> versus V<sub>VCC-SENSE</sub>, yielding Gain and Offset terms for the linear fit. The Linearity (%) plot is calculated as:

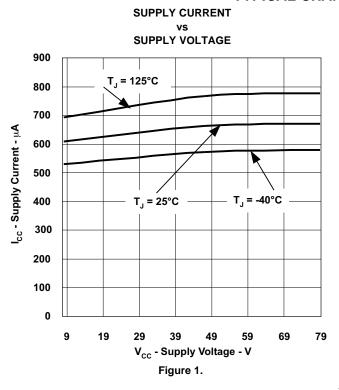
$$Linearity(\%) = \frac{V_{IMON} - \left[ \left( Gain \times V_{VCC-SENSE} \right) + Offset \right]}{\left[ \left( Gain \times V_{VCC-SENSE} \right) + Offset \right]} \times 100$$
(4)

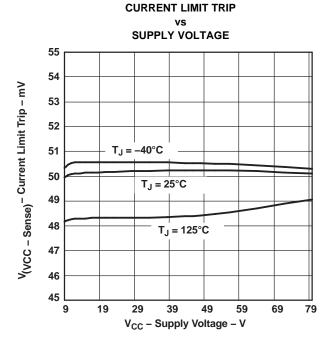
FLT: This active low, open drain output asserts (goes low) when the fault timer expires after a prolonged over current or an OV is detected. FLT is open drain whenever UVEN, POR, or UVLO are not satisfied. FLT is latched in the TPS2492, clearing when the latch is reset. FLT clears automatically in the TPS2493 when a power-up retry occurs. V<sub>FLT</sub> can be greater than V<sub>VCC</sub> because it's ESD protection is only with respect to ground. FLT may be left open or tied to GND when not used.

OV: The over-voltage monitoring pin is programed with a resistor divider such as R1 - R3 in the Typical Application Circuit. This function forces GATE and FLT low while the OV condition exists. While V<sub>OV</sub> exceeds its threshold, the strong GATE pull down (125 mA) is applied for up to 100 µs, followed by the 2 mA pull down. The GATE pull down and FLT are released as soon as the OV condition is cleared. Tie OV to GND if not used.



#### **TYPICAL CHARACTERISTICS**





# GATE PULL UP CURRENT vs SUPPLY VOLTAGE

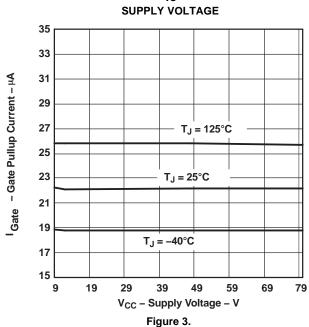
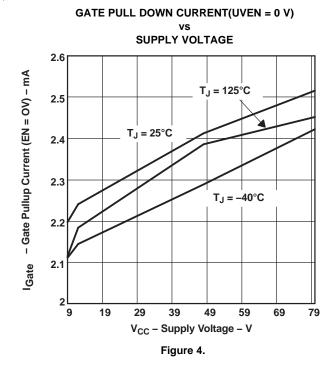


Figure 2.



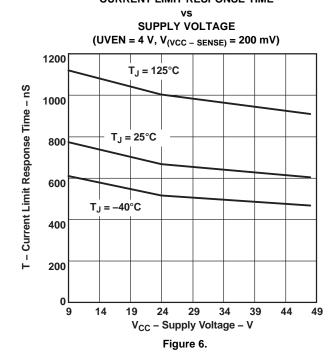


# **TYPICAL CHARACTERISTICS (continued)**

#### **GATE PULL DOWN CURRENT**

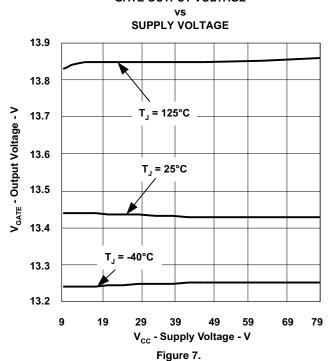
## SUPPLY VOLTAGE (UVEN = 4 V, $V_{(VCC - SENSE)}$ = 200 mV) 215 I<sub>Gate</sub> – Gate Pulldown Current – mA 195 $T_J = -40^{\circ}C$ 175 $T_J = 25^{\circ}C$ 155 135 $T_J = 125^{\circ}C$ 115 95 75 <del>-</del> 39 49 59 79 19 29 69 V<sub>CC</sub> - Supply Voltage - V

# CURRENT LIMIT RESPONSE TIME



# GATE OUTPUT VOLTAGE

Figure 5.



#### TIMER PULL UP CURRENT

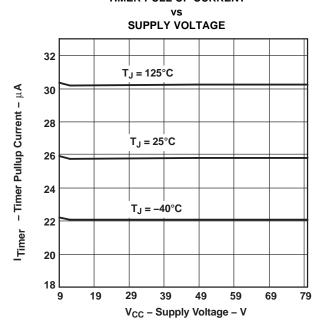
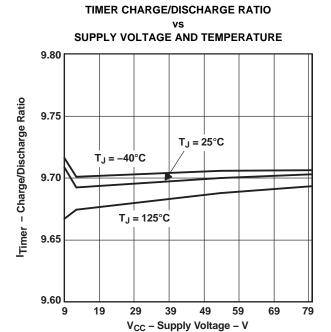


Figure 8.



# **TYPICAL CHARACTERISTICS (continued)**



# T<sub>J</sub> = 25°C 1.349 1.349 1.347 1.346 T<sub>J</sub> = -40°C

39

Figure 11.

V<sub>cc</sub> - Supply Voltage - V

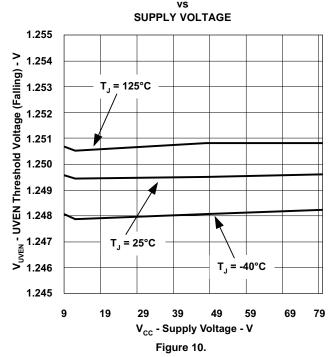
49

59

69

79

UVEN AND OV THRESHOLD VOLTAGE (falling)



SUPPLY VOLTAGE

0.8

0.7

0.6

0.5

0.4

0.3

0.2

0.1

T = 125°C

**LINEARITY** 

0 10 20 30 40 50

V<sub>CC-VSENSE</sub> - Supply Voltage - mV

Figure 12.

60

1.345

9

19

Linearity - %

0

-0.1

-0.2



#### APPLICATION INFORMATION

#### **Basic Operation**

The TPS2492/93 features include:

- 1. Adjustable under-voltage and over-voltage lockout;
- 2. Turn-on inrush limit;
- 3. High-side gate drive for an external N-channel FET;
- 4. FET protection (power limit and current limit);
- Adjustable overload timeout;
- 6. Output current monitor;
- 7. Status output;
- 8. Charge-complete indicator for downstream converter sequencing; and
- 9. Optional automatic restart mode.

The TPS2492/93 features power-limiting FET protection that allows independent control of current limit (to set maximum full-load current), power limit (to keep FET in its safe operating area), and overload time (to control temperature rise). The power limiting feature controls the V and I across the FET to protect it, and does not control load power. This protection is a specialized form of foldback output limiting. Given a constant power dissipation, computation of peak junction temperature is straight forward. The TPS2393 provides a small operating duty cycle into a short, reducing the average temperature rise of the FET to levels similar to normal operation in many systems. This prevents overheating and failure with prolonged exposure to an output short. The typical application circuit, and oscilloscope plots of Figure 13 and Figure 17 demonstrate many of the functions described above.

#### **Board Plug-In (Figure 13)**

Only the bypass capacitor charge current and small bias currents are evident when a board is first plugged in as seen in Figure 13. The TPS2492/93 is held inactive with GATE, PROG, and TIMER held low, and with  $\overline{PG}$  and  $\overline{FLT}$  open drain, for less than 1 ms while internal voltages stabilize. Then GATE, PROG, TIMER,  $\overline{FLT}$  and  $\overline{PG}$  are released and the part begins sourcing current to the GATE pin because UVEN is high and OV is low. The external FET begins to turn on while the voltage across it,  $V_{(SENSE-OUT)}$ , and current through it,  $V_{(VCC-SENSE)}/R_{SENSE}$ , are monitored. Current initially rises to the value which satisfies the power limit engine ( $P_{LIM}/V_{VCC}$ ) since the output capacitor was discharged. The shape of the input current waveform shows the operation of the FET power limit. In this case, the 5-A current limit is never reached as the output reaches full charge. This is likely due to the limited gate slew rate.



# TIMER and PG Operation (Figure 13)

The TIMER pin charges  $C_T$  as long as limiting action continues, and discharges at a 1/10 charge rate when limiting stops. If the voltage on  $C_T$  reaches 4 V before the output is charged, the external <u>FET</u> is turned off and either a latch-off or restart cycle commences, depending on the part type. The open-drain <u>PG</u> output provides a deglitched end-of-charge indication which is based on the voltage across the external FET. <u>PG</u> is useful for preventing a downstream DC-to-DC converter from starting while  $C_O$  is still charging. <u>PG</u> goes active (low) about 9 ms after  $C_O$  is charged. This delay allows the external FET to fully turn on and any transients in the power circuits to end before the converter starts up. The resistor pull-up shown on pin <u>PG</u> in the <u>Typical Application Circuit</u> only demonstrates operation; the actual connection to the converter depends on the application. Timing can appear to terminate early in some designs if operation transitions out of the power limit mode into a gate charge-rate limited mode at low  $V_{DS}$  values. This effect sometimes occurs because gate capacitances,  $C_{GD}$  and  $C_{GS}$ , are nonlinear with applied voltage, getting larger at smaller voltage. This can be seen in Figure 13.

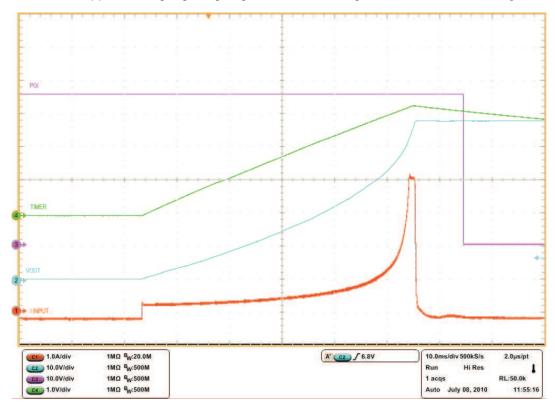


Figure 13. Basic Board Insertion



#### Action of the Constant Power Engine (Figure 14)

The calculated power dissipated in the external FET,  $V_{DS}$  x  $I_{D}$ , is computed under the same startup conditions as Figure 13. The current of the external FET, labeled  $I_{IN}$ , initially rises to the value that satisfies the constant power engine; in this case it is 25 W / 48 V = 0.52 A. The 25-W value is programmed into the engine by setting the PROG voltage using R4 and R5.  $V_{DS}$  of the external FET, which is calculated as  $V_{(SENSE-OUT)}$ , falls as  $C_{O}$  charges, thus allowing the external FET drain current to increase. This is the result of the internal constant power engine adjusting the current limit reference to the GATE amplifier as  $C_{O}$  charges and  $V_{DS}$  falls. The calculated device power in Figure 14, labeled POWER, is seen to be reasonably constant within the limitations of circuit tolerance and acquisition noise. A fixed current limit is implemented by clamping the constant power engine output to 50 mV when  $V_{DS}$  is low. This protection technique can be viewed as a specialized form of foldback limiting; the benefit over linear foldback is that it yields the maximum output current from a device over the full range of  $V_{DS}$  while still protecting the device.

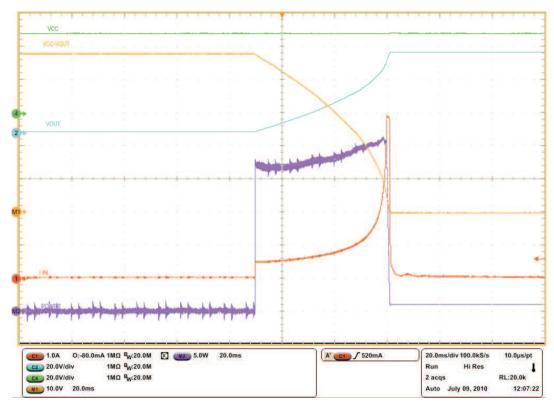


Figure 14. Computation of the External FET Stress During Startup



## Response to a Hard Output Short (Figure 15, Figure 16, and Figure 17)

Figure 15 shows the short circuit response over the full time-out period. An output short is applied, causing the voltage to fall, limiter action begin, and the fault timer to start. The external FET current is actively controlled by the power limiting engine and gate amplifier circuit while the TIMER pin charges  $C_T$  to the 4-V threshold. Once this threshold is reached, the TPS2492/93 turns off the external FET. The TPS2492 latches off until either the input voltage drops below the UVLO threshold or UVEN cycles through the false (low) state. The TPS2493 will attempt a restart after going through a timing cycle. Figure 16 demonstrates the operation of FLT during a short circuit. FLT remains false (open drain) until the TIMER has expired.

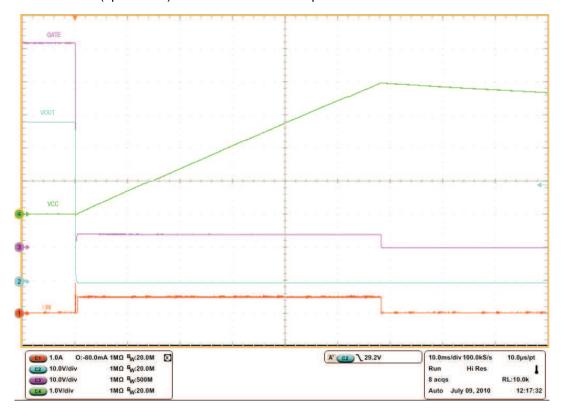


Figure 15. Current Limit Overview



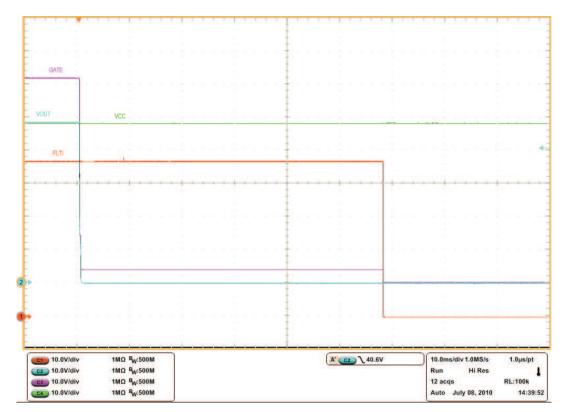


Figure 16. FLT Operation

The TPS2492/93 responds rapidly to a short circuit as seen in Figure 17. The falling OUT voltage is the result of the external FET and  $C_O$  currents through the short circuit impedance. The internal GATE clamp causes the GATE voltage to follow the output voltage down and subsequently limits the negative  $V_{GS}$ . The  $I_{IN}$  waveform includes current into an input 47  $\mu$ F capacitor. M1 drain current has a peak value in excess of the waveform, and terminates when  $V_{GATE}$  approaches  $V_{OUT}$ . The rapidly rising fault current overdrives the GATE amplifier causing it to overshoot and rapidly turn the external FET off by sinking current to ground. At a time beyond the extent of Figure 17, but within the scope of Figure 15, the FET will be slowly turned back on as the GATE amplifier recovers. The operating point will settle to the current or power limit, and finally the TIMER will expire and the FET will turn off.

Limited input voltage overshoot appears in Figure 17 because a local 47- $\mu$ F bypass capacitor and 1000  $\mu$ F distribution capacitor were used. The input voltage overshoots as the input current abruptly drops due to the stored energy in the input wiring inductance. The exact waveforms seen in an application depend upon many factors including parasitics of the voltage distribution, circuit layout, and the short itself.

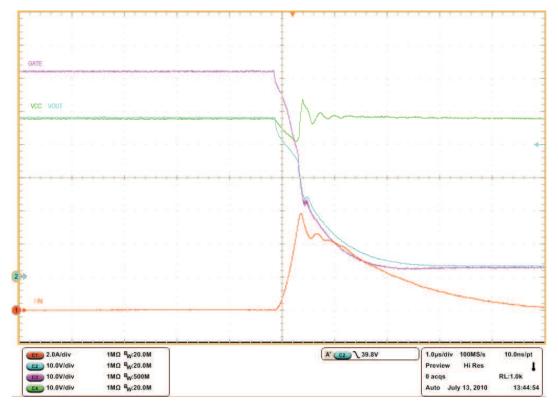


Figure 17. Current Limit Onset



#### **Automatic Restart (Figure 18)**

The TPS2493 automatically initiates a restart after a fault has caused it to turn off the external FET. Internal control circuits use  $C_T$  to count 16 cycles before re-enabling the external FET. This sequence repeats if the fault persists. TIMER has a 1:10 charge-to-discharge current ratio, and uses a 1-V lower threshold. The fault-retry duty cycle specification in the Electrical Characteristics Table quantifies this behavior. This small duty cycle often reduces the average short-circuit power dissipation to levels associated with normal operation and reduces the need for additional measures such as oversized heatsinking. Figure 18 demonstrates that the initial timing cycle starts with  $V_{TIMER}$  at zero V, subsequent cycles start with  $V_{TIMER}$  at 1 V, and a successful restart occurs after a 16 cycle delay.

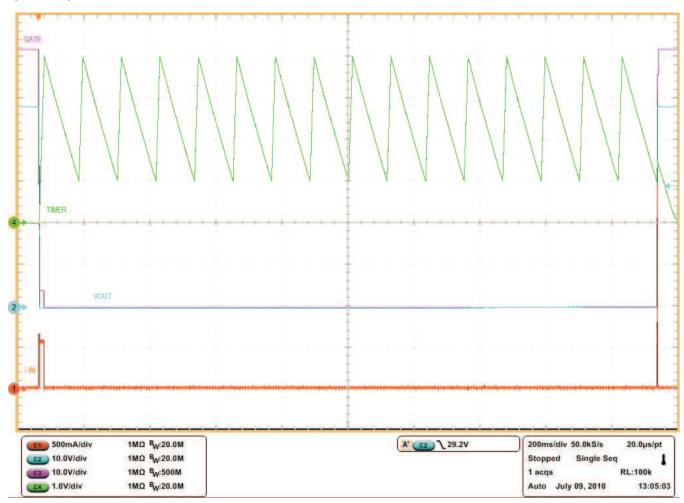


Figure 18. TPS2492/93 Restart Cycle Timing



#### **Application Design Example**

The following example illustrates the design and component selection process for a TPS2492/93 application. Figure 19 shows the application circuit for this design example. The requirements of this design are:

Nominal System Voltage: 12 V

Maximum Operating System Voltage: 13.5 V

Overvoltage Threshold: 14.5 V
 Undervoltage Threshold: 9.5 V
 Steady-state Load Current: 40 A
 Load Capacitance: 1000 µF

Maximum Ambient Temperature: 50°C

Maximum Static Junction Temperature 125°C

Maximum Transient Junction Temperature: 150°C

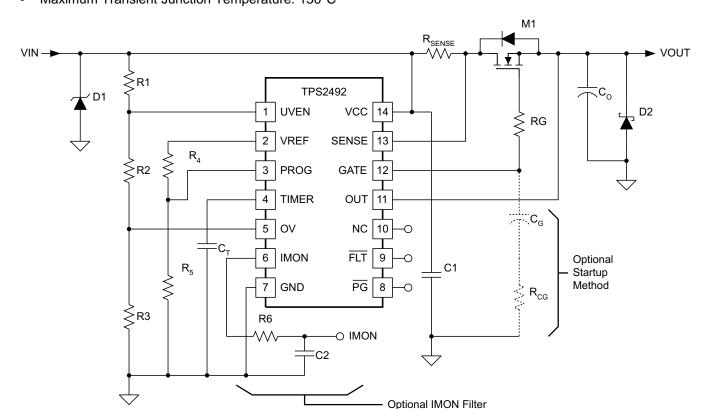


Figure 19. TPS2492/93 Design Example Schematic



#### 1. Choose R<sub>SENSE</sub>

Calculate  $R_{SENSE}$  using a multiplier factor of 1.2 (20%) for  $V_{SENSE}$  and  $R_{SENSE}$  tolerance along with some additional margin.

$$R_{\text{SENSE}} = \frac{V_{\text{SENSE}}}{1.2 \times I_{\text{LIMIT}}} = \frac{50 \text{mV}}{1.2 \times 40 \text{A}} = 1.042 \text{m}\Omega$$
(5)

Choose  $R_{SENSE}$  = 1 m $\Omega$ , resulting in a nominal 50 A current limit.

$$I_{\text{LIMIT(MAX)}} = \frac{V_{\text{SENSE(MAX)}}}{R_{\text{SENSE}}} = \frac{55mV}{1m\Omega} = 55A \tag{6}$$

$$P_{RSENSE} = I_{LIMIT(MAX)}^2 \times R_{SENSE} = 55A^2 \times 1m\Omega = 3.025W$$
(7)

Multiple sense resistors in parallel should be considered.

#### 2. Choose M1

Select the M1  $V_{DS}$  rating allowing for maximum input voltage and transients. Then select an operating  $R_{DSON}$ , package, and cooling to control the operating temperature. Most manufacturers list  $R_{DSON(MAX)}$  at 25°C and provide a typical characteristics curve from which values at other temperatures can be derived. The next equation can be used to estimate desired  $R_{DSON(MAX)}$  at the maximum operating junction temperature of  $T_{J(MAX)}$ . (usually 125°C).  $T_{A(MAX)}$  is the maximum expected ambient temperature. Assume that a thermal resistance,  $R_{\theta JA}$  of 10 °C/W can be achieved by reinforcing the typical 40°C/W for a 1² inch copper pad with copper on multiple layers and some airflow.

$$R_{DSON(MAX)} = \frac{T_{J(MAX)} - T_{A(MAX)}}{R_{\theta JA} \times I_{LIMIT(NOM)}^2} = \frac{125^{\circ}C - 50^{\circ}C}{10 \frac{^{\circ}C}{W} \times (50A)^2} = 3m\Omega \text{ at } T_{J} = 125^{\circ}C$$
(8)

Assume that we are able to find a suitable FET with an  $R_{DSON}$  of 0.74 m $\Omega$  at 25°C and 1.18 m $\Omega$  at 125°C. These devices are in a package such as a D2PAK with a large copper base and very low  $R_{\theta JC}$ .

The junction-to-ambient thermal resistance,  $R_{\theta JA}$ , depends upon the package style chosen and the details of heat-sinking and cooling including the PCB layout. Actual "in-system" temperature measurements will be required to validate thermal performance.



#### 3. Choose the Power Limit $P_{LIM}$ and the PROG Resistors, $R_4$ and $R_5$

M1 dissipates large amounts of power during power-up or output short circuit. Power limit,  $P_{LIM}$  should be set to prevent the M1 die temperature from exceeding a short term maximum temperature,  $T_{J(MAX2)}$ . Short term  $T_{J(MAX2)}$  may be set as high as 150°C (specified on FET datasheet) while still leaving ample margin for the typical manufacturer's rating of 175°C. The R4 and R5 resistors set  $V_{PROG}$ , programming the FET power dissipation. Assume that  $R_{\theta JA}$  is 10 °C/W,  $R_{\theta JC}$  is 0.2 °C/W, and  $R_{\theta CA}$  is 9.8 °C/W for the device we chose above.  $P_{LIM}$  can be estimated as follows:

$$P_{\text{LIM}} = \frac{0.7 \times \left[ T_{\text{J(MAX2)}} - \left( R_{\theta \text{CA}} \times I_{\text{LIMIT(NOM)}}^2 \times R_{\text{DSON}} \right) - T_{\text{A(MAX)}} \right]}{R_{\theta \text{JC}}} = 249W \tag{9}$$

Where  $R_{\theta CA}$  is the M1 plus PCB case-to-ambient thermal resistance,  $R_{\theta JC}$  is M1 junction-to-case thermal resistance,  $R_{DSON}$  is M1 channel resistance at the maximum operating temperature, and the factor of 0.7 accounts for the tolerance of the constant power engine. In this case we know that power limit is less than  $I_{LIMIT} \times V_{IN}$  and that power limit will control operation during a short circuit.

It is often advantageous to use a transient value of  $R_{\theta JC}$  to get a usable solution, that is a  $V_{PROG}$  within the recommended range. If a current/power limited startup is used, transient  $R_{\theta JC}$  should be based on the TIMER period (see below). FET manufacturers typically provide transient thermal resistance in graphic format on their datasheet. Additional information can be found in SLVA158.

The following equations calculate  $V_{PROG}$  and R4 using an assumed  $R_5$  = 20 k $\Omega$ .

$$V_{PROG} = \frac{P_{LIM}}{10 \times I_{LIM}} = \frac{249}{10 \times 50} = 0.498V$$
(10)

$$R_4 = R_5 \times \left(\frac{V_{REF}}{V_{PROG}} - 1\right) = 140.6k\Omega \tag{11}$$

Choose  $R_4$  = 140 k $\Omega$ . The recommended minimum  $V_{PROG}$  is 0.4 V. This is based on tolerance and accuracy of the constant power engine making very low power-limited designs highly variable. Some suggestions to get larger  $P_{LIM}$  values are to start with a low static operating junction temperature, and to utilize the transient thermal impedance (energy absorbing nature) of the package.

The output I vs. V<sub>OUT</sub> curve for this configuration is shown in Figure 20.

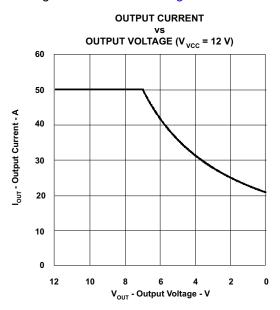


Figure 20. TPS2492/93 Power and Current Limit Curve

22



# 4. Choose the TIMER Capacitor, C<sub>T</sub> and Turn-On Time

The turn on time  $t_{\text{ON}}$ , represents the time it takes the circuit to charge up the output capacitance  $C_{\text{O}}$  and load.  $C_{\text{T}}$  programs the fault time and should be chosen so that the fault timer does not terminate prior to completion of start up. The turn on time is a function of the type of control; current limit, power limit, or dV/dt control. The following equations calculates  $t_{\text{ON}}$  for the power limit and current limit cases, and assume that only  $C_{\text{O}}$  draws current during startup.

For 
$$P_{LIM} < V_{VCC(MAX)} \times I_{LIMIT(NOM)}$$
:  $t_{ON} = \frac{C_O \times P_{LIM(ACT)}}{2 \times I_{LIMIT(NOM)}^2} + \frac{C_O \times V_{VCC(MAX)}^2}{2 \times P_{LIM(ACT)}} \left(Power Limit\right)$  (12)

For 
$$P_{LIM} \ge V_{VCC(MAX)} \times I_{LIMIT(NOM)}$$
:  $t_{ON} = \frac{C_O \times V_{VCC(MAX)}}{I_{LIMIT(NOM)}} (Current Limit Only)$ 
(13)

$$t_{\text{ON}} = \frac{C_{\text{O}} \times P_{\text{LIM}}}{2 \times I_{\text{LIMIT(NOM)}}^2} + \frac{C_{\text{O}} \times V_{\text{VCC(MAX)}}^2}{2 \times P_{\text{LIM}}} = \frac{1000 \,\mu F \times 249 W}{2 \times 50^2 A} + \frac{1000 \,\mu F \times 13.5 V^2}{2 \times 249 W} = 416 \,\mu \text{s}$$
(14)

The next equation computes  $C_T$  for a TPS2492 application. TPS2492/93 TIMER current source and capacitor tolerances are accounted for.

$$C_{T} = \frac{I_{SOURCE(MAX)}}{V_{TMR-TH(MAX)}} \times t_{ON} \times (1 + C_{O-TOL} + C_{T-TOL})$$
(15)

$$C_{T} = \frac{36\mu A}{4.1V} \times 416\mu s \times (1 + 0.2 + 0.1) = 4.75nF$$
(16)

Choose  $C_T$  = 6.8 nF assuming a 20% output capacitor tolerance and a 10% timing capacitor tolerance. Equation 16 is written around startup for a TPS2492, however during a restart (after a fault) of a TPS2493,  $C_T$  charges from 1 V to 4.1 V, requiring a  $V_{TMR-TH(MAX)}$  value of 3.1V.

The maximum TIMER period may be calculated using the minimum TIMER charge current and maximum value of  $C_T$ . Use this period to determine the transient  $R_{\theta JC}$  in step 3. While this is beyond the scope of this example, it may lead to some iteration.



# 5. Choose the Turn-On and Over-voltage Divider, R<sub>1</sub> - R<sub>3</sub>

Per our system design requirements above, both over-voltage shutdown and under-voltage shutdown are desired. Equations for calculating the thresholds are:

$$V_{OV_{-}H} = \frac{V_{OV} \times R3}{(R1 + R2 + R3)}$$
(17)

$$V_{UVEN_{-}H} = \frac{V_{UV} \times (R2+R3)}{(R1+R2+R3)}$$
(18)

Assume R3 is 1 k $\Omega$  and use the following procedure to determine R1 and R2.

$$R1+R2 = \frac{R3 \times (V_{OV}-V_{OV\_H})}{(V_{UV\_H})} = \frac{1k\Omega \times (14.5V - 1.35V)}{1.35V} = 9.7407k\Omega$$
(19)

$$R2+R3 = \frac{V_{UVEN\_H} \times ((R1+R2)+R3)}{(V_{UV})} = \frac{1.25V \times (9.7407k\Omega + 1k\Omega)}{9.5V} = 1.4133k\Omega$$
(20)

$$R2 = (R2 + R3) - R3 = 1.4133k\Omega - 1k\Omega = 0.4133k\Omega$$
(21)

$$R1 = (R1 + R2) - R2 = 9.7407k\Omega - 0.4133k\Omega = 9.3275k\Omega$$
(22)

Selecting standard 1% values and scaling up by a factor of 10 to reduce power loss results in (R1 = 93.1 k $\Omega$ ), (R2 = 4.12 k $\Omega$ ), and (R3 = 10 k $\Omega$ ).

#### **Alternative Inrush Designs**

#### Gate Capacitor (dV/dt) Control

The TPS2492/93 can be used with applications that require constant turn-on currents. The current is controlled by a single capacitor from the GATE terminal to ground with a series resistor. M1 appears to operate as a source follower (following the gate voltage) in this implementation. Again assuming that the output capacitor charges without additional loading, choose a time to charge,  $t_{\rm ON}$ , based on the load capacitor,  $C_{\rm O}$  input voltage  $V_{\rm I}$ , and desired charge current  $I_{\rm CHARGE}$ . When power limiting is used ( $V_{\rm PROG} < V_{\rm REF}$ ) choose  $I_{\rm CHARGE}$  to be less than  $P_{\rm LIM}$   $V_{\rm VCC}$  to prevent the fault timer from starting. The fault timer starts only if power or current limit is invoked.

$$t_{\text{ON}} = \frac{C_{\text{O}} \times V_{\text{VCC}}}{I_{\text{CHARGE}}} \tag{23}$$

Use the following equation to select the gate capacitance,  $C_G$ . It has been assumed that the external added (linear) capacitor is much larger than the FET capacitance.  $C_{GD}$  is the gate capacitance of M1, and  $I_{GATE}$  is the TPS2492/93 nominal gate charge current.  $C_{GD}$  is non-linear with applied  $V_{DG}$ . An averaged estimate may be made using the FET  $V_{GS}$  vs  $Q_G$  curve. Divide the charge accumulated during the plateau region by the plateau  $V_{GS}$  to get  $C_{GD}$ . As shown in Figure 19, a series resistor of about 1 k $\Omega$  should be used in series with  $C_G$  to avoid slowing the turnoff.

$$C_{G} = \frac{I_{GATE} \times t_{ON}}{V_{VCC}} - C_{GD}$$
(24)

If neither power nor current limit faults are invoked during turn on,  $C_T$  can be chosen for fast transient turnoff response. Considerations are junction temperature rise (as above), anticipated system noise, and possible peak overloads due to input voltage or load transients. Generally the period should be much less than the  $t_{ON}$  of step 4 above.



#### Additional Design Considerations

#### Calculation Tool SLVC033

The calculation tool for the TPS2490/91, SLVC033, may be used with the TPS2492/93. For accurate results, the timer current constants need to be updated. This may be accomplished using the Excel Tools / Protection command along with the password provided in the tool (spreadsheet).

#### Use of PG to Control Downstream Converters

Use the  $\overline{PG}$  pin to control and sequence a downstream DC/DC converter. If this is not done a long time delay may be needed to allow  $C_O$  to fully charge before the converter starts. This practice will avoid having the converter attempt to operate at a low input voltage, drawing large currents. This mode of converter operation has the potential to form a stable operating point with the hotswap output I-V characteristic, preventing the system from starting.

#### **IMON Filtering**

The internal monitoring circuits leave a small amount of residual noise at about 2.5 kHz on the IMON output. While this does not contribute significant error at output voltages on the order of 1 V, better accuracy at low outputs will benefit from an R-C filter. Figure 19 demonstrates this filtering with elements R6 and C2. An example solution is a 1 k $\Omega$  resistor and a 1.5 nF capacitor. A buffer (e.g. unity-gain opamp) may be required if the output is used by a circuit that draws significant current.

#### **Output Clamp Diode**

Inductive loads or wiring inductance on the output may drive the OUT pin below GND when the circuit is unplugged or during current limit. The OUT pin can be protected by D2 (see Figure 19) between the TPS2492/93 OUT to GND pins. The OUT pin can withstand a short transient to -1 V.

#### **Input Clamp TVS**

Energy stored in the inductance of input wiring has the capability to drive the input voltage up if the (load) current is abruptly decreased. An example is a hard short on OUT rapidly raising the input current above the current limit threshold, which is then abruptly driven to zero when the current limit gains control after several microseconds. Combinations of input capacitance and transient voltage suppressor diodes (TVS - a type of Zener Diode) can aid in controlling the voltage overshoot. This is demonstrated by D1 and C1 of Figure 19. While a small bypass capacitor is recommended, the TVS is better able to control the voltage without the drawback of large input capacitance.

#### **Gate Clamp Diode**

The TPS2492/93 has a relatively well-regulated gate voltage of 12 V to 16 V, even at low supply voltages. A small clamp Zener from gate to source of M1, such as a BZX84C7V5, is recommended if  $V_{GS}$  of M1 is rated below this.

# **Input Bypass Capacitance**

The input bypass capacitor, C1 per Figure 19 should be used to provide a low impedance local source of current and control the supply dv/dt on the VCC pin.



#### Adding External GATE-OUT Capacitance

Avoid directly placing ceramic capacitors directly across M1 gate to source when bypassing for ESD or noise is desired. Add some small resistance in series with the capacitor if absolutely required. If the resistance is not present, the added phase shift may encourage high frequency oscillation of the combined input and output L-C circuits during startup conditions.

#### **High Gate Capacitance Applications**

If OUT falls very rapidly during a fault, the FET  $V_{GS}$  can be driven high by the  $C_{GD}$  -  $C_{GS}$  voltage divider of  $(V_{SENSE}$  -  $V_{OUT})$ . Given enough capacitance and dv/dt, the internal 14-V GATE to OUT clamp may not have the capability to fully control the voltage. An external gate clamp Zener diode may be required to protect the FET if this is the case.

When gate capacitor dV/dT control is used, a 1-k $\Omega$  resistor in series with  $C_G$  is recommended, as shown in Figure 19.

#### **Output Short Circuit Measurements**

Repeatable short-circuit testing results are difficult to obtain. The many details of source bypassing, input leads, circuit layout and component selection, output shorting method, relative location of the short, and instrumentation all contribute to varying results. The actual short itself exhibits a certain degree of randomness as it microscopically bounces and arcs. Care in configuration and methods must be used to obtain realistic results. Do not expect to see waveforms exactly like those in the data sheet since every setup differs.

#### **Applications Using the Retry Feature (TPS2493)**

Applications using the retry feature may want to estimate fault retry time. The TPS2493 will retry (enable M1 to attempt turn on) once for every 16 timer charge/discharge cycles (15 cycles between 1 V and 4 V, 1 cycle between 0 V and 4 V).

$$T_{RETRY} = C_T \times 19.6 \times 10^6 \tag{25}$$

#### M1 Selection

Use of a power FET in the linear region places large, long term stresses on the distributed junction. FETs whose safe operating area (SOA) curves display multiple slopes on the same line (e.g. a line whose time parameter is a constant) in the region of high voltage and low current generally are susceptible to secondary breakdown and are not strong candidates for this application. An example of a good choice is found in the Typical Application Circuit where the line at 10 ms shows no breaks in slope. The best device for the application is not always the lowest  $R_{\text{DSON}}$  device.

#### **Layout Considerations**

Good layout practice places the power devices D1,  $R_{SENSE}$ , M1, and  $C_{O}$  so power flows in a sequential, linear fashion. A ground plane under the power and the TPS2492/93 is desirable. The TPS2492/93 should be placed close to the sense resistor and FET using a Kelvin type connection to achieve accurate current sensing across  $R_{SENSE}$ . A low-impedance GND connection is required because the TPS2492/93 can momentarily sink upwards of 100 mA from the gate of M1. The GATE amplifier has high bandwidth while active, so keep the GATE trace length short. The PROG, TIMER, OV, and UVEN pins have high input impedances, therefore keep their input leads short. Oversize power traces and power device connections to assure low voltage drop and good thermal performance.





# **REVISION HISTORY**

Cł	nanges from Original (July 2010) to Revision A	Page
•	Changed marketing status	





27-Aug-2010

#### **PACKAGING INFORMATION**

Orderable Device	Status <sup>(1)</sup>	Package Type	Package Drawing	Pins	Package Qty	Eco Plan <sup>(2)</sup>	Lead/ Ball Finish	MSL Peak Temp <sup>(3)</sup>	Samples (Requires Login)
TPS2492PW	ACTIVE	TSSOP	PW	14	90	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	Request Free Samples
TPS2492PWR	ACTIVE	TSSOP	PW	14	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	Purchase Samples
TPS2493PW	ACTIVE	TSSOP	PW	14	90	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	Request Free Samples
TPS2493PWR	ACTIVE	TSSOP	PW	14	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	Purchase Samples

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

**TBD:** The Pb-Free/Green conversion plan has not been defined.

**Pb-Free** (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes. **Pb-Free** (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

(3) MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

**Important Information and Disclaimer:** The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

# PACKAGE MATERIALS INFORMATION

www.ti.com 25-Aug-2010

# TAPE AND REEL INFORMATION





	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



#### \*All dimensions are nominal

Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TPS2492PWR	TSSOP	PW	14	2000	330.0	12.4	6.9	5.6	1.6	8.0	12.0	Q1
TPS2493PWR	TSSOP	PW	14	2000	330.0	12.4	6.9	5.6	1.6	8.0	12.0	Q1

www.ti.com 25-Aug-2010



#### \*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
TPS2492PWR	TSSOP	PW	14	2000	346.0	346.0	29.0
TPS2493PWR	TSSOP	PW	14	2000	346.0	346.0	29.0

PW (R-PDSO-G14)

# PLASTIC SMALL OUTLINE



NOTES:

- A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M—1994.
- B. This drawing is subject to change without notice.
  - Sody length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0,15 each side.
- Body width does not include interlead flash. Interlead flash shall not exceed 0,25 each side.
- E. Falls within JEDEC MO-153



# PW (R-PDSO-G14)

# PLASTIC SMALL OUTLINE



NOTES:

- A. All linear dimensions are in millimeters.
- B. This drawing is subject to change without notice.
- C. Publication IPC-7351 is recommended for alternate designs.
- D. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC-7525 for other stencil recommendations.
- E. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.



#### IMPORTANT NOTICE

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, modifications, enhancements, improvements, and other changes to its products and services at any time and to discontinue any product or service without notice. Customers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All products are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its hardware products to the specifications applicable at the time of sale in accordance with TI's standard warranty. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by government requirements, testing of all parameters of each product is not necessarily performed.

TI assumes no liability for applications assistance or customer product design. Customers are responsible for their products and applications using TI components. To minimize the risks associated with customer products and applications, customers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any TI patent right, copyright, mask work right, or other TI intellectual property right relating to any combination, machine, or process in which TI products or services are used. Information published by TI regarding third-party products or services does not constitute a license from TI to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of TI information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. Reproduction of this information with alteration is an unfair and deceptive business practice. TI is not responsible or liable for such altered documentation. Information of third parties may be subject to additional restrictions.

Resale of TI products or services with statements different from or beyond the parameters stated by TI for that product or service voids all express and any implied warranties for the associated TI product or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

TI products are not authorized for use in safety-critical applications (such as life support) where a failure of the TI product would reasonably be expected to cause severe personal injury or death, unless officers of the parties have executed an agreement specifically governing such use. Buyers represent that they have all necessary expertise in the safety and regulatory ramifications of their applications, and acknowledge and agree that they are solely responsible for all legal, regulatory and safety-related requirements concerning their products and any use of TI products in such safety-critical applications, notwithstanding any applications-related information or support that may be provided by TI. Further, Buyers must fully indemnify TI and its representatives against any damages arising out of the use of TI products in such safety-critical applications.

TI products are neither designed nor intended for use in military/aerospace applications or environments unless the TI products are specifically designated by TI as military-grade or "enhanced plastic." Only products designated by TI as military-grade meet military specifications. Buyers acknowledge and agree that any such use of TI products which TI has not designated as military-grade is solely at the Buyer's risk, and that they are solely responsible for compliance with all legal and regulatory requirements in connection with such use.

TI products are neither designed nor intended for use in automotive applications or environments unless the specific TI products are designated by TI as compliant with ISO/TS 16949 requirements. Buyers acknowledge and agree that, if they use any non-designated products in automotive applications, TI will not be responsible for any failure to meet such requirements.

Following are URLs where you can obtain information on other Texas Instruments products and application solutions:

Products		Applications	
Audio	www.ti.com/audio	Communications and Telecom	www.ti.com/communications
Amplifiers	amplifier.ti.com	Computers and Peripherals	www.ti.com/computers
Data Converters	dataconverter.ti.com	Consumer Electronics	www.ti.com/consumer-apps
DLP® Products	www.dlp.com	Energy and Lighting	www.ti.com/energy
DSP	dsp.ti.com	Industrial	www.ti.com/industrial
Clocks and Timers	www.ti.com/clocks	Medical	www.ti.com/medical
Interface	interface.ti.com	Security	www.ti.com/security
Logic	logic.ti.com	Space, Avionics and Defense	www.ti.com/space-avionics-defense
Power Mgmt	power.ti.com	Transportation and Automotive	www.ti.com/automotive
Microcontrollers	microcontroller.ti.com	Video and Imaging	www.ti.com/video
RFID	www.ti-rfid.com	Wireless	www.ti.com/wireless-apps
RF/IF and ZigBee® Solutions	www.ti.com/lprf		

**TI E2E Community Home Page** 

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265 Copyright © 2011, Texas Instruments Incorporated

e2e.ti.com